# NavX<sup>®</sup>-NCS Professiona Data Sheet | August 2011

Multi-GNSS Platform Multi-Frequency Platform Flexible Capability Licensing Modular HW Plug-Ins

11 ....

User Prope

pation | Hardware | Driama

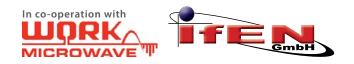
446.3

Coherent GPS, Galileo, GLONASS, QZSS and SBAS signals Up to 9 L-band frequencies at the same time freely selectable Extend your GNSS capabilities by simple SW licensing Scalable from 12 to 108 signal channels according to your needs

Your future-proof investment in the leading edge test solution.

**Multi-Frequency GNSS RF Signal Generator** 

The test reference for multi-frequency GNSS professional applications.





# NavX<sup>®</sup>-NCS Professional

# Features

# **Multi-GNSS** Capabilities

- GPS L1, L2/L2C, L5
- Galileo E1, E5, E6
- GLONASS G1, G2
- QZSS L1
- SBAS (WAAS, EGNOS, MSAS, GAGAN)

# Scalability & Flexibility

- 12 108 signal channels (up to 9 MERLIN modules)
- Internal noise generator module
- Free mapping of channels to modulations and GNSSs by software configuration
- Extension of capability by SW license

# Connectivity

- Remote control capability
- 1 PPS and 10 MHz reference

# **Usability and Control**

- Advanced graphical user interface (GUI) for scenario definition, simulation configuration and control
- Intuitive operation allows easy modification of variables from preset defaults
- Full constellation, user and vehicle motion control
- Flexible user trajectory generation (pre-defined, from file or via editor)
- Data logging to a file during scenario run-time for analysis
- Start on external trigger

# **Comprehensive Simulation**

- Space and user segment
- Extensive signal propagation modelling (multipath, ionosphere, troposphere, terrain)
- Antenna gain and phase pattern
- Lever arm effects modelling
- Differential GNSS corrections

The NavX<sup>®</sup>-NCS Professional has been designed to fully meet the requirements for GNSS RF research and development testing of multi-frequency GNSS safety and professional applications. The NavX<sup>®</sup>-NCS Professional is the leading solution on the market providing all 9 L-band frequencies for GPS, Galileo, GLONASS, QZSS, SBAS and beyond in one box simultaneously.

Due to its superior technology, the outstanding performance features of the NavX<sup>®</sup>-NCS Professional are beyond the capabilities of any other signal generator on the market today. Besides, you avoid the extra complexity and cost of using additional signal generators or intricate architectures involving several hardware boxes, while improving reliability and not compromising on functionality.

It is the only GNSS simulator in the market today offering both flexibility and scalability with full multi-constellation capability, all in a single chassis.

Unlike other GNSS simulators, the NavX<sup>\*</sup>-NCS gives you full control on scenario generation. Full GNSS simulation power just a few clicks away!

# **Benefits**

# Ready for Today – Prepared for Tomorrow

With up to 108 signal channels, current multi-GNSS receivers can be tested with just one NavX®-NCS Professional. For more demanding applications, even receivers with 216 channels can be covered today by just two NavX®-NCS Professional simulators.

# Future-Proof Investment

The NavX°-NCS hardware is GNSS system agnostic. That means the NavX®-NCS can generate any known GNSS signal today, and also cope with modulations and signal structures yet to be developed. The NavX®-NCS is a safe investment for years to come.

# Custom Made ... for You

Because of its unique hardware and software architecture, you can configure the NavX®-NCS with just what you need today. No need to be tied to features you may never need. Add new capabilities as your testing needs grow.

# No Testing Down-Time

Because we know that time is money, unlike other existing simulators, the NavX<sup>\*</sup>-NCS can be upgraded by a software license. No need to send your NavX<sup>\*</sup>-NCS back to us. Tell us what you need, and in a matter of minutes (not weeks!) you'll be up and running with a complete new GNSS system, frequency options, etc.

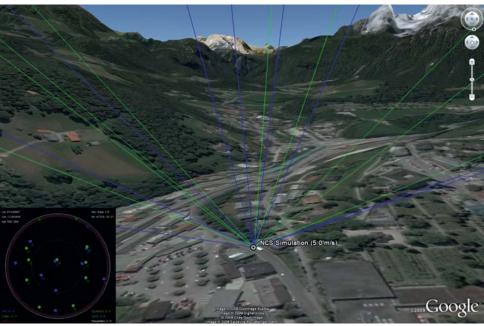
# Full Advanced Simulation Control

Our user-friendly GUI allows you to detail satellite orbits, user trajectories, various vehicle motion models (6DOF), signal characteristics and propagation. And the list goes on. Please contact us to know more on how far your testing can go with the NavX<sup>®</sup>-NCS Professional.



The NavX<sup>\*</sup>-NCS Professional consists of the signal generation hardware and a control computer including the pre-installed Windows®-based 'NCS Control Center', a flexible and powerful software for simulation configuration and interactive control.

The NavX<sup>\*</sup>-NCS Professional can also be connected to other hardware or be integrated into existing test environments. Various input and output interfaces like 1PPS, a hardware trigger, input for external oscillators offer full flexibility for a variety of applications.













Visualization of NavX<sup>®</sup>-NCS simulation data

NavX<sup>®</sup>-NCS Control Center

# Innovation

# **MERLIN Technology**

With the introduction of the powerful MERLIN simulation engine at the heart of the NavX<sup>\*</sup>-NCS Professional, it is for the first time possible to simulate any GNSS system and frequency by using the same hardware. Any GNSS constellation and frequency can be freely assigned to any MERLIN simulation engine installed.

Re-using the same MERLIN simulation engines by just adding additional system licenses enables a new level of GNSS constellation and frequency configuration, which was not existing before, providing the user with full flexibility and outstanding benefit.



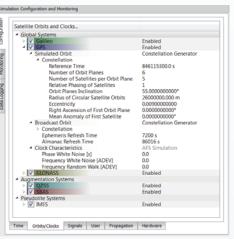
MERLIN signal generation engine



Nine MERLIN engines fit into one NCS Professional

# NavX<sup>®</sup>-NCS Professional

# **Control Center SW**



## Fully flexible constellation editor

Γ	User Environment	
	Motion Type     Start Position     Latitude     Longitude     Height     Motion Characteristics	Import User Trajectory Ellipsoidal (WGS 84) 48.17150000° 11.80800000° 525.00 m
	Trajectory File Trajectory Type Start After	munich.trj Global 120.0 s
	<ul> <li>Multipath Satellite System</li> <li># S/V to generate Fixed Offset MP</li> </ul>	Fixed Offset Multipath GPS 2
	<ul> <li>PRN #1</li> <li>Path Delay</li> <li>Doppler Offset</li> <li>Power Loss</li> <li>PRN #2</li> <li>Path Delay</li> <li>Doppler Offset</li> <li>Power Loss</li> </ul>	21 5.00 m 0.500 Hz 3.00 dB 15 8.00 m 0.050 Hz 5.00 dB
	Elevation Mask Antenna Gain Pattern	5.0 * Spherical

# Comprehensive user trajectory generation

Cenerate KML Files     Voer Position     KML File Name     Position Label     Custom User Icon     Licon Scaling Factor     Altitude Mode     Custom Settings     Satellite Constellation     KML File Name     Display Mode     Econ     Satellite Kon     Satellite     Satellite Kon     Satellite     Satellite Kon     Satellite     Satel	Ves CL/NCSData/Output/UserPos.kml NCS Simulation 1.0 Clamp to ground Ves CL/NCSData/Output/SatPos.kml Earth orbiting
KML File Name Position Jabel Custom User Icon Icon Scaling Factor Altitude Mode 9 Camera Settings 4 Satellite Constellation KML File Name Display Mode Custom Satellite Icon Scaling Factor for Satellite Heigh 4 Line-04-Sight Nectors	C\NCSData\Output\UserPos.kml NCS Simulation 1.0 Clamp to ground Yes C\NCSData\Output\SatPos.kml
Position Label Custon User Icon Icon Scaling Factor Atitude Mode > Camene Settings - Satelline Constellation IKM, File Name Display Mode Custon Satellite Icon Scaling Factor for Satellite Heigh - Line-OF-Spit Netons	NCS Simulation 1.0 Clamp to ground Yes C\NCSData\Output\SatPos.kml
Custom User Icon Icon Scaling Factor Altitude Mode b Camera Settings Statellite Constellation KML fire Name Display Mode Custom Satellite Icon Scaling Factor for Satellite Heigh J Line-OF-Sight Vectors	1.0 Clamp to ground Yes C\NCSData\Output\SatPos.kml
Icon Scaling Factor Altitude Mode > Camera Settings < Satellite Constellation KML file Name Display Mode Custom Satellite Icon Scaling Factor for Satellite Heigh < Line-0F-Sight Vectors	Clamp to ground Yes C:\NCSData\Output\SatPos.kml
Altitude Möde Camera Settings Satellite Constellation KML File Name Display Mode Custom Satellite Loon Scaling Factor for Satellite Heigh Vine-Of-Sight Vectors	Clamp to ground Yes C:\NCSData\Output\SatPos.kml
Camera Settings     Satellite Constellation     KML File Name     Display Mode     Custom Satellite Icon     Scaling Factor for Satellite Heigh     Line-Of-Sight Vectors	Yes C:\NCSData\Output\SatPos.kml
<ul> <li>Satellite Constellation KML File Name Display Mode Custom Satellite Icon Scaling Factor for Satellite Heigh</li> <li>Line-Of-Sight Vectors</li> </ul>	C:\NCSData\Output\SatPos.kml
KML File Name Display Mode Custom Satellite Icon Scaling Factor for Satellite Heigh Line-Of-Sight Vectors	C:\NCSData\Output\SatPos.kml
Display Mode Custom Satellite Icon Scaling Factor for Satellite Heigh 4 Line-Of-Sight Vectors	
Custom Satellite Icon Scaling Factor for Satellite Heigh 4 Line-Of-Sight Vectors	Earth orbiting
Scaling Factor for Satellite Heigh 4 Line-Of-Sight Vectors	
Line-Of-Sight Vectors	its 1.00
	Ves
	C\NCSData\Output\LosData.kml
Scaling Factor for LOS Endpoints	
Altitude Mode	Relative to ground
Clamp LOS Starting Points to Gro	
<ul> <li>User Trajectory</li> </ul>	Yes
KML File Name	C:\NCSData\Output\TrjData.kml
Altitude Mode	Clamp to ground
<ul> <li>Multipath Rays</li> </ul>	Yes
KML File Name	C:\NCSData\Output\MpRays.kml
Altitude Mode	Absolute
Save Skyplots	No
Save World Map	No
KML File Viewer	C:\Program Files\Google\Google Ea.

Outstanding data visualization



# **Simulation Capabilities**

# Supported GNSS and Augmentation System Capability

- Galileo (E1 BOC/CBOC, E5ab AltBOC, E6)
- GPS (L1, L2/L2C, L5)
- GLONASS (G1, G2)
- QZSS (L1)
- SBAS (L1) (EGNOS, WAAS, MSAS, GAGAN)

# **Configuration and Control**

- Time, date and user position
- Support of user trajectories
- Pre-configured simulations available

# Space and User Segment

- Import YUMA almanac files
- Definition of orbit parameters per satellite
- Single-step constellation generator
- Definition of satellite clock characteristics
- Definition of user and satellite antenna gain and phase pattern
- Definition of various user vehicle motion models (6DOF)
- Definition of arbitrary elevation masks

- Predefined user trajectories available
- Import of NMEA files
- Integrated trajectory editor
- · Preview of trajectory characteristics

# Analysis and Interactive Control

- Display and monitoring of simulation data during run time
- Export of simulation data to file
- Interactive control of signal parameters during run time

# **Signal Specifications**

# **Frequency Bands**

1	1,575.42	MHz
2/L2C	1,227.60	MHz
5	1,176.45	MHz
o E1	1,575.42	MHz
o E5ab	1,191.79	MHz
o E6	1,278.75	MHz
ASS G1	1,602.00	MHz
ASS G2	1,246.00	MHz
	2/L2C 5 5 E1 5 E5ab 5 E6 ASS G1	2/L2C       1,227.60         5       1,176.45         5       1,575.42         5       1,191.79         5       1,278.75         ASS G1       1,602.00

# **Modulation Schemes**

- BPSK, QPSK, BOC, CBOC, FDMA
- AltBOC, Tri-Phase Interplex (CASM)

# Signal Dynamics

<ul> <li>Max. velocity (LOS):</li> </ul>	± 22,800 m/s
<ul> <li>Max. acceleration:</li> </ul>	± 1,500 m/s <sup>2</sup>
• Max. jerk:	± 15,600 m/s <sup>3</sup>

# Signal Accuracy

<ul> <li>Pseudorange:</li> </ul>	< 1 mm RMS
<ul> <li>Pseudorange rate:</li> </ul>	< 1 mm/s RMS
<ul> <li>Interchannel bias:</li> </ul>	zero
Intermodule bias:	< + 1.0 ns

# Signal Quality

<ul> <li>Spurious (max.):</li> </ul>	< -70 dBc
Harmonics (max.):	< -40 dBc
• Phase noise (max.):	0.005 rad RMS
• Frequency stability (24h):	$< \pm 5 \times 10^{-10}$

# Nominal RF Signal Levels

RF monitoring port:	- 60 dBm
RF signal output(max.):	- 90 dBm
RF signal output(min.):	- 170 dBm

# Signal Level Control

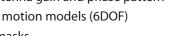
• Digital attenuation:

- RF attenuation:
- 0.0 40.0 dB 0.0 - 40.0 dB









# **Signal Propagation**

- · Definition of terrain obstructions
- Configuration of various multipath scenarios
- · Definition of tropospheric and ionospheric influences

# **User Trajectories**

**System Capabilities and Specifications** 

# Hardware

## Input Interfaces

- Power supply: 85 264 VAC, 40-70 Hz
- Ethernet:
- 10 MHz reference (sine wave):
- Hardware trigger input:

# **Output Interfaces**

- RF signal output (front side):
- RF monitoring port (rear panel):
- BNC • 10 MHz reference (sine wave):
- BNC • 1 pulse per second (1 PPS):





NCS Professional rear side

# **Plug-In Modules**

- MERLIN:
- up to 9 modules 12 one GNSS

RJ45

BNC

BNC

Ν

SMA

• Channels per module: GNSS per module:



**MERLIN** signal generation modules

## **Physical Parameters**

- Mounting: 19" rack mounting, 2 HU
- Size (H x W x D): 86 x 483 x 570 mm
- Weight:
- Power consumption:
  - < 120 W +10° to +55° C
- Operating Temperature:
- Storage Temperature:

# **Control Computer**

- Laptop
- Operating systems:
- Control SW:

INTEL i7 based MS Windows® 7 NCS Control Center

< 10 kg

-40° to +70°



## **NCS Control Computer**

Disclaimer Specification subject to change without prior notice

at 0.1 dB steps (per module) at 0.1 dB steps (per channel)

# NavX<sup>®</sup>-NCS Professi Sales Worldwide | August 2011

# Headquarter

IFEN GmbH Alte Gruber Straße 6 85586 Poing Germany

# **Global Sales**

For additional product information or sales orders outside of the EMEA area, please contact our distributors and sales agents directly.

The current list of distributors is available on www.ifen.com/distributors



Made in Germany

